

## SOME PROBLEMS YOU SHOULD BE ABLE TO DO

I've attempted to make a list of the main calculations you should be ready for on the exam, and included a handful of the more important formulas. There are no examples here: for that, check my lecture worksheets accompanying the corresponding sections. Please let me know if you notice any mistakes or omissions!

I don't recommend studying exclusively from this list – it is inevitable that I have left something out. Be sure to look at old exams, problem sets, etc. as well.

A few topics we covered only briefly are in italics. It couldn't hurt to look, but don't worry about these too much.

### CHAPTER 11

#### 11.1 and 11.2: Vectors in the plane and vectors in three dimensions.

- Compute basic vector operations: addition/subtraction, scalar multiplication, magnitude.
- Know how to interpret these both algebraically and geometrically.
- Find vector from point  $P$  to point  $Q$ .
- Find a unit vector in the direction of a given vector (or a vector with some other specified length)
- Midpoint of a line segment.
- Equation of a sphere.
- Statics problems (balancing forces).*

#### 11.3: Dot products.

- Compute the dot product of two vectors algebraically ( $a_1b_1 + a_2b_2 + a_3b_3$ ) and geometrically ( $|\mathbf{a}| |\mathbf{b}| \cos \theta$ )
- Compute the angle between two vectors
- Compute and interpret  $\text{proj}_{\mathbf{v}} \mathbf{u}$  and  $\text{scal}_{\mathbf{v}}(\mathbf{u})$ :

$$\text{proj}_{\mathbf{v}} \mathbf{u} = \left( \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \right) \mathbf{v}, \quad \text{scal}_{\mathbf{v}} \mathbf{u} = |\mathbf{u}| \cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|}.$$

- Work done by a constant force.
- Parallel and normal components of a force.

#### 11.4: Cross products.

- Compute the cross product of two vectors.
- Find the area of a triangle with given vertices.
- Find the area of a parallelogram with given vertices.

**11.5: Lines and curves in space.**

- Parametrize a straight line
- You always need to know two things: a point  $\mathbf{r}_0$  that the line goes through, and a vector  $\mathbf{v}$  in the direction of the line (often you will need to do some work to find  $\mathbf{v}$ , depending on what information is given to you!). Then use the formula  $\mathbf{r}(t) = \mathbf{r}_0 + t\mathbf{v}$  (and think about the bounds)
  - between two given points
  - through a point and perpendicular to a given plane
  - through a point and perpendicular to two given lines
  - tangent to a curve  $\mathbf{r}(t)$  at  $t = a$
  - given as the intersection of two planes
- Parametrize other simple curves (circles)
- Check whether lines intersect
- Take a limit (by taking the limit of each component)

**11.6: Calculus of vector-valued functions.**

- Find the derivative  $\mathbf{r}'(t) = \frac{d\mathbf{r}}{dt}$
- Find tangent vector to a curve at time  $t$
- Find unit tangent vector to a curve
- Integrate a vector-valued function (by integrating each component)

**11.7: Motion in space.**

- Find velocity, acceleration, and speed.
- Find position from velocity and velocity from acceleration, given an initial condition  $\mathbf{v}(0)$  or  $\mathbf{a}(0)$ .
- Movement in a gravitational field.*

**11.7: Length of curves.**

- The arc length of  $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$  is

$$\int_a^b \sqrt{f'(t)^2 + g'(t)^2 + h'(t)^2} dt = \int_a^b |\mathbf{r}'(t)| dt.$$

This is the distance traveled by a particle moving along the curve from  $t = a$  to  $t = b$ .

- Find arc length in polar.
- Check whether a path is parametrized by arc length.

## CHAPTER 12

**12.1: Planes and surfaces.**

- Find the equation for a plane with normal vector  $\langle a, b, c \rangle$  passing through  $(x_0, y_0, z_0)$ .
- Find the equation for a plane through three given points
- Find the equation for a line given as the intersection of two planes.
- Check whether two planes are orthogonal.
- Equations for cylinders*

**12.2: Quadric surfaces.**

- Sketch the graph of a quadric surface by drawing the  $xy$ -,  $xz$ -, and  $yz$ -traces, or some other traces parallel to the coordinate planes.
- Find the intersection of a line with a quadric surface.

**12.3: Limits of functions of several variables.**

- Compute the limit of a function of two variables.
- Use the two-path test to show that a limit does not exist.

**12.4 & 12.5: Partial derivatives.**

- Compute the partial derivative of a function  $f(x, y)$
- Compute the four second-order partial derivatives of a function
- Use the chain rule to compute partial derivatives of functions of two or three variables.
- Apply implicit differentiation to an expression  $F(x, y) = 0$

**12.6: Directional derivatives and the gradient.**

- Compute (and interpret) the directional derivative  $D_{\mathbf{u}}f$
- Find the gradient  $\nabla f$ .
- Find direction of fastest ascent/descent and the rate of fastest ascent/descent for a function  $f(x, y)$ .
- Find directions of 0 increase.
- Sketch level curves of a function, and tangent directions to level curves.

**12.7: tangent planes and linear approximation.**

- Find tangent plane to implicit surface  $F(x, y, z) = 0$  at a point  $(x_0, y_0, z_0)$ .
- Find tangent plane to explicit surface  $z = f(x, y)$  at a point  $(x_0, y_0, z_0)$ .
- Find the linear approximation to  $f(x, y)$  near a point  $(a, b)$  and use this to approximate values of  $f$ .
- Work with differentials.*

**12.8: Maxima and minima.**

- Find the critical points of a function.
- Use the second derivative test to classify the critical points as max/min/saddle.
- Find the global max/min of a function  $f(x, y)$  on a region  $R$ :
  - (1) Find critical points inside  $R$
  - (2) Find relative max/min on the boundary
  - (3) Make a list of all the “interesting points” and compute values of  $f$  there to find the true max and min.

**12.9: Lagrange multipliers.**

- Use Lagrange multipliers to find the maxima and minima of  $f(x, y)$  subject to the constraint  $g(x, y) = 0$
- Key formula:  $\nabla f(x, y) = \lambda \nabla g(x, y)$ .  
Translate this into three equations in the three variables  $x, y$ , and  $\lambda$  and solve
- Translate a word problem into a constrained optimization problem.

## CHAPTER 13

**13.1: Double integrals.**

- Set up and compute the double integral of a function  $f(x, y)$  on a rectangular region  $a \leq x \leq b, c \leq y \leq d$ .
- Find the average value of  $f(x, y)$  on such a region.
- Fubini's theorem: you can change the order of the integral.

**13.2: Double integrals over other regions.**

- Evaluate a double integral where the inner bounds depend on the outer variable.
- Sketch the region of integration for a double integral, given the bounds.
- Give the bounds on a double integral, given a description of the region.
- Change the order of integration in a double integral over a non-rectangular region.

**13.3: Double integrals in polar coordinates.**

- Sketch the region of integration for a double integral in polar
- Evaluate a double integral in polar.
- Convert a double integral in rectangular coordinates into polar:
  - (1) Write the bounds in polar
  - (2) Write the function in polar (substitute  $r \cos \theta$  for  $x$ ,  $r \sin \theta$  for  $Y$ )
  - (3) Write  $r dr d\theta$  instead of  $dx dy$ .

**13.4: Triple integrals.**

- Evaluate a triple integral.
- Set up the bounds for a triple integral in rectangular coordinates (important shapes: rectangular regions, tetrahedral regions)
- Change the order of integration in a triple integral.

**13.5: Cylindrical spherical coordinates.**

- Find the rectangular coordinates for a point given  $(r, \theta, z)$

$$x = r \cos \theta, \quad y = r \sin \theta, \quad z = z.$$

- Find the cylindrical coordinates for a point given  $(x, y, z)$ :
- Set up the bounds for a triple integral in cylindrical coordinates (Important shapes: cylinder, paraboloid.)
- Convert a rectangular integral into cylindrical coordinates and evaluate (usual three steps: convert the bounds, convert the function, use  $r dr d\theta dz$ ).
- Find the rectangular coordinates for a point given  $(\rho, \theta, \phi)$ :

$$x = \rho \sin \phi \cos \theta, \quad y = \rho \sin \phi \sin \theta, \quad z = \rho \cos \phi.$$

- Set up the bounds for a triple integral into spherical coordinates (Important shapes: spheres, hemispheres, ice cream cones.)
- Convert a rectangular integral into spherical coordinates and evaluate (usual three steps: convert the bounds, convert the function, use  $\rho^2 \sin \phi d\rho d\phi d\theta$ ).

**13.7: Change of variables in multiple integrals.**

- Given a change of coordinates  $x = g(u, v)$ ,  $y = h(u, v)$ , compute the Jacobian  $J(u, v)$ :

$$J(u, v) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} = \frac{\partial(x, y)}{\partial(u, v)}.$$

- Change an integral in terms of  $x$  and  $y$  to an integral in terms of  $u$  and  $v$ :

$$\iint_R f(x, y) dA = \iint_S f(g(u, v), h(u, v)) |J(u, v)| dA.$$

- Find the  $uv$  bounds for an integral from the  $xy$  bounds (often helpful; convert the equation for each edge of the region into an equation involving  $uv$ , and sketch the corresponding region in the  $uv$ -plane).

## CHAPTER 14

**14.1: Vector fields.**

- Sketch a vector field from the equation.  
 Write a formula for a vector field given a description.  
 Compute the gradient field  $\mathbf{F} = \nabla f(x, y)$  for a function  $f(x, y)$

**14.2: Line integrals.**

- Compute the line integral  $\int_C f(x, y) ds$  of a scalar function along a path.  
 • Method: parametrize the path  $C$  by  $\mathbf{r}(t) = \langle x(t), y(t) \rangle$ . Use bounds as parametrization as bounds on integral, plug in  $x$  and  $y$  to  $f$ , and use  $|\mathbf{r}'(t)| dt$  for the  $ds$ :

$$\int_C f ds = \int_a^b f(x(t), y(t)) |\mathbf{r}'(t)| dt.$$

- Compute the line integral of a  $\int_C \mathbf{F} \cdot d\mathbf{r}$  of a vector function along a path (i.e. a circulation integral).  
 • Parametrize  $C$  by  $\mathbf{r}(t)$ , then plug in  $x$  and  $y$  to  $\mathbf{F}$ , and dot that with  $\mathbf{r}'(t)$  to get a function of  $t$ .  
 Compute the flux of a vector field across a path  $C$   
 • Same method, but use  $\mathbf{n} = \langle y(t), -x(t) \rangle$  instead of  $\mathbf{r}'(t)$  in the above.

**14.3: Conservative vector fields.**

- Check whether a 2D vector field  $\mathbf{F} = \langle f, g \rangle$  is conservative.  
 Check whether a 3D vector field  $\mathbf{F} = \langle f, g, h \rangle$  is conservative.  
 Find a potential function  $\phi(x, y)$  for a conservative vector field.  
 Use the fundamental theorem for line integrals to compute the line integral of a conservative field along a path  $C$ :

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \phi(\text{end}) - \phi(\text{begin}).$$

Note: integral is independent of path.

**14.4: Green's theorem.**

- Compute the divergence and curl of a 2D vector field (both are scalar functions, not vector fields).
- Be able to apply both versions of Green's theorem to double integrals over a region  $R$ :

- Circulation form:

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_R \text{curl } \mathbf{F} \, dA$$

- Flux form:

$$\oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \iint_R \text{div } \mathbf{F} \, dA$$

- Use Green's theorem to turn a line integral over a complicated path from  $A$  to  $B$  into a line integral over a simpler path from  $A$  to  $B$  and a double integral over the region between the two paths.

**14.5: Divergence and curl.**

- Compute the divergence of a 3D vector field  $\nabla \cdot \mathbf{F}$  (this is a scalar function).
- Compute the curl of a 3D vector field:

$$\begin{aligned} \nabla \times \mathbf{F} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & g & h \end{vmatrix} \\ &= \left( \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) \mathbf{i} + \left( \frac{\partial f}{\partial z} - \frac{\partial h}{\partial x} \right) \mathbf{j} + \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \mathbf{k} \end{aligned}$$

NB: This is another vector field.

**14.6: Surface integrals.**

- Parametrize a surface in 3D
  - (1) Cylinder of radius  $a$ ;  $x = a \cos u$ ,  $y = a \sin u$ ,  $z = v$
  - (2) Sphere of radius  $a$ :  $x = a \sin u \cos v$ ,  $y = a \sin u \sin v$ ,  $z = a \cos u$ .
  - (3) Graph  $z = f(x, y)$  (for example,  $z = 2(x^2 + y^2)$ ):  $x = u$ ,  $y = v$ ,  $z = f(u, v)$ .
- Next, know how to compute the tangent vectors  $\mathbf{t}_u$ ,  $\mathbf{t}_v$ , and the normal vector  $\mathbf{t}_u \times \mathbf{t}_v$ .
- Compute surface integrals of scalar functions:  $\iint_S f(x, y, z) \, dS$ . Steps to convert to a double integral in  $u, v$ :
  - (1) The bounds are the bounds for your parametrization
  - (2) Rewrite the function in terms of  $u$  and  $v$  (plug in your parametrization for  $x, y$ , and  $z$ )
  - (3) Use  $|\mathbf{t}_u \times \mathbf{t}_v| \, du \, dv$  for  $dS$ .
- Compute flux integrals of vector fields across a surface:  $\iint_S \mathbf{F} \cdot \mathbf{n} \, dS$ . Steps to convert to a double integral in  $u, v$ :
  - (1) The bounds are the bounds for your parametrization
  - (2) Rewrite the function in terms of  $u$  and  $v$  (plug in your parametrization for  $x, y$ , and  $z$ )
  - (3) Plug in  $x, y, z$  from parametrization to  $\mathbf{F}$
  - (4) Dot that with  $\mathbf{t}_u \times \mathbf{t}_v$  and integrate the result  $du \, dv$ .

**14.7: Stokes' theorem.**

- Be able to apply Stokes' theorem, either to turn a computation of the flux of a curl into a circulation integral, or to turn a circulation integral into the flux of a curl.

$$\iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} \, dS = \oint_C \mathbf{F} \cdot d\mathbf{r}.$$

- Know how to compute both sides!
- Know which way to go around the curve  $C$  to make this work (right-hand rule).
- Apply Stokes' theorem on regions with multiple boundaries.

**14.8: Divergence theorem.**

- Be able to apply divergence theorem, in either direction.

$$\oiint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iiint_D \nabla \cdot \mathbf{F} \, dV.$$

- Know how to compute both sides!