

Announcements

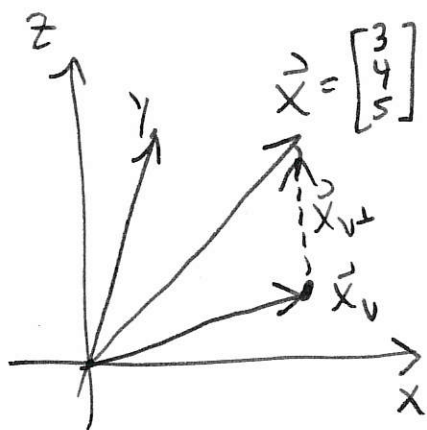
- Pick up your exam on the way out
- OH tomorrow cancelled; email to set a time. (Fri or Mon)
- Today: orthogonal projection.

Geometric observation:

\vec{x} a vector in \mathbb{R}^3

$U = xy\text{-plane}$, a subspace.

you can always write \vec{x} as $\vec{x}_U + \vec{x}_{U^\perp}$, where \vec{x}_U is in $xy\text{-plane}$, and \vec{x}_{U^\perp} is perpendicular to U .



$$\vec{x}_U = \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix}$$

$$\vec{x}_{U^\perp} = \begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix}$$

the same thing can be done for any plane U , doesn't have to be $xy\text{-plane}$.

$$\begin{array}{ccc} \vec{x} & = & \vec{x}_U + \vec{x}_{U^\perp} \\ & & \uparrow \quad \uparrow \\ & & \text{in } U \quad \text{in } U^\perp \end{array}$$

Finding $\vec{x}_W, \vec{x}_{W^\perp}$ is easy if W is xy -plane,
but there's a way to do it for any other plane.

If $W \subset \mathbb{R}^n$ is a subspace, and $\vec{w}_1, \dots, \vec{w}_p$
is an orthogonal basis for W , then any vector
 \vec{x} can be written as $\vec{x}_W + \vec{x}_{W^\perp}$, where \vec{x}_W in W ,

\vec{x}_{W^\perp} perp to W .

$$\vec{x}_W = \underbrace{\frac{\vec{x} \cdot \vec{w}_1}{\vec{w}_1 \cdot \vec{w}_1}}_{\text{scalar}} \vec{w}_1 + \underbrace{\frac{\vec{x} \cdot \vec{w}_2}{\vec{w}_2 \cdot \vec{w}_2}}_{\text{scalar}} \vec{w}_2 + \dots + \underbrace{\frac{\vec{x} \cdot \vec{w}_p}{\vec{w}_p \cdot \vec{w}_p}}_{\text{scalar}} \vec{w}_p.$$

then $\vec{x}_{W^\perp} = \vec{x} - \vec{x}_W$.

\vec{x}_W is definitely in W , since it's a linear combo of
basis vectors

Example
W = XY-plane.

$$\vec{w}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \vec{w}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

$$\vec{x} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$$

Formula says:

$$\vec{x}_W = \frac{\begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \frac{\begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$= \frac{3}{1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \frac{4}{1} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix} \quad \checkmark$$

$$\vec{x}_{W^\perp} = \vec{x} - \vec{x}_W = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} - \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix}.$$

Notes:

1. \vec{x}_W is also called $\text{proj}_W \vec{x}$.

2. \vec{x}_W is the vector in W that's as close as possible to \vec{x} .
(distance as small as possible)

3. - the formula required an orthogonal basis!

- our methods for finding bases don't give orthogonal bases, most of the time.

- Fri: Gram-Schmidt ~~algorithm~~: orthonormalization:
given a basis, convert to an orthogonal basis.
this can be used in the formula.