

1. Consider the 2×2 matrix $A = \begin{bmatrix} 2 & -1 \\ 6 & -3 \end{bmatrix}$.
 - (a) What is the column picture for $A\mathbf{x} = \mathbf{b}$?
 - (b) For what vectors \mathbf{b} is there a solution?
 - (c) What are all solutions to $A\mathbf{x} = \mathbf{0}$?
 - (d) Pick a non-zero \mathbf{b} for which there is a solution. What are all solutions to $A\mathbf{x} = \mathbf{b}$? Sketch the set of solutions.
 - (e) Every solution in (c) is of the form $\mathbf{x} = \mathbf{x}_p + \mathbf{x}_n$, where \mathbf{x}_p is some fixed particular solution. How does \mathbf{x} vary when we pick different \mathbf{x}_n in the nullspace?

2. Let A be the matrix

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 6 & 7 & 8 \\ 0 & 0 & 6 & 6 & 6 \end{bmatrix}.$$

- (a) Put A in echelon form, and reduced echelon form.
 - (b) What are the free and pivot variables? Find a special solution for each free variable.
 - (c) Find all solutions to $A\mathbf{x} = \mathbf{0}$.
 - (d) What is the rank of A ? What does this tell you about the rows and columns? Which columns are combinations of earlier columns?
 - (e) What are the possible ranks of a 3×5 matrix? What are the possible numbers of special solutions of a 3×5 matrix?
 - (f) For what vectors \mathbf{b} does $A\mathbf{x} = \mathbf{b}$ have a solution?
 - (g) Find all solutions to $A\mathbf{x} = \begin{pmatrix} 1 \\ 4 \\ 6 \end{pmatrix}$.
3. Which of the following subsets of \mathbb{R}^3 are subspaces?
 - (a) The line parameterized by $\mathbf{v}(t) = (1, 2, 3) + (1, 0, 0)t$.
 - (b) The line parameterized by $\mathbf{v}(t) = (1, 2, 3) + (2, 4, 6)t$.
 - (c) The set of points at distance 1 from the origin.
 - (d) The plane defined by the equation $x + 2y + 3z = c$ (for different values of c).

For those which are not subspaces, what is the span of the vectors in the set?

4.
 - (a) Let $\mathbf{v}_1 = (1, 2, 3)$, $\mathbf{v}_2 = (4, 5, 6)$, and $\mathbf{v}_3 = (7, 8, 9)$. Show that \mathbf{v}_1 and \mathbf{v}_2 are linearly independent, but \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 are linearly dependent.
 - (b) What is a basis for the space of symmetric 3×3 matrices? What is the dimension of this space?
 - (c) How about for upper triangular 3×3 matrices?
 - (d) Give a basis for the set of 3×3 upper-triangular matrices with trace 0 (i.e. such that the sum of the diagonal elements is 0).

5. (*) This is a challenge problem to highlight the analogy with the principle of superposition in 18.03 – it doesn't have too much to do with what we're studying now, so don't worry about it!

Let V be the set of all infinitely differentiable functions of period 2π .

- (a) Check that V is a vector space.
- (b) Check that the map $D = \frac{\partial}{\partial t^2} + I$ gives a linear map from V to V .
- (c) What is the nullspace of D ?
- (d) What are all solutions in V of $Df = \cos 2t$? $Df = \cos t$?
- (e) Represent the function f as a vector, with entries its Fourier coefficients. What is the $\infty \times \infty$ "matrix" for D ? Can you describe the range of D ?