

1. Let \mathbf{v} be the vector $\mathbf{v} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$. Let W be the subspace of \mathbb{R}^3 given by all vectors perpendicular to \mathbf{v} .

(a) Find a basis for W (hint: W is the nullspace of the 1×3 matrix $[1 \ 1 \ 1]$).

To find the nullspace of $[1 \ 1 \ 1]$, just use parametric vector form as usual. Reduced echelon form of the augmented matrix (with an extra column of 0s) is given by

$$[\ 1 \ 1 \ 1 \ | \ 0]$$

The variables x_2 and x_3 are free, while x_1 is a pivot. The general solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -s - t \\ s \\ t \end{bmatrix} = s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

A basis for W is given by the two vectors

$$\mathbf{x}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{x}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

(b) Find an orthonormal basis for W .

The two vectors we got are not an orthonormal basis: they aren't even orthogonal to each other. So we need to use the Gram-Schmidt process. First we construct an orthogonal basis:

$$\mathbf{v}_1 = \mathbf{x}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$
$$\mathbf{v}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1/2 \\ -1/2 \\ 1 \end{bmatrix}.$$

This has $\mathbf{v}_2 \cdot \mathbf{v}_1 = 0$, like we want. But it's still not an orthogonal basis: for that, we need to divide each of the vectors by its length.

$$\mathbf{u}_1 = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} -1/\sqrt{6} \\ -1/\sqrt{6} \\ \sqrt{2/3} \end{bmatrix}.$$

- (c) The vector $\begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix}$ is perpendicular to \mathbf{v} , so it's in the subspace W . Write this vector as a linear combinations of your orthonormal basis vectors from (b).

There's a quick rule for this: $\mathbf{v} = c_1\mathbf{u}_1 + c_2\mathbf{u}_2$ where

$$c_1 = \mathbf{v} \cdot \mathbf{u}_1 = -2/\sqrt{2} - 1/\sqrt{2} = -\frac{3\sqrt{2}}{2}$$
$$c_2 = \mathbf{v} \cdot \mathbf{u}_2 = -2/\sqrt{6} + 1/\sqrt{6} - \sqrt{2/3} = -\sqrt{3/2}.$$

So

$$\mathbf{v} = -\frac{3\sqrt{2}}{2}\mathbf{u}_1 - \sqrt{\frac{3}{2}}\mathbf{u}_2.$$

- (d) Let $\mathbf{p} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$. What point on W is closest to \mathbf{p} ?

We want $\text{proj}_W \mathbf{p}$, which is given by

$$\text{proj}_W \mathbf{p} = (\mathbf{p} \cdot \mathbf{u}_1)\mathbf{u}_1 + (\mathbf{p} \cdot \mathbf{u}_2)\mathbf{u}_2 = \cdots = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

- (e) Let A be the 3×2 matrix whose columns are the vectors in your answer to (a). Find a QR decomposition for A .

We have Q given by the columns \mathbf{u}_1 and \mathbf{u}_2 :

$$Q = \begin{bmatrix} -1/\sqrt{2} & -1/\sqrt{6} \\ 1/\sqrt{2} & -1/\sqrt{6} \\ 0 & \sqrt{2/3} \end{bmatrix}.$$

Then

$$R = Q^T A = \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{6} & -1/\sqrt{6} & \sqrt{2/3} \end{bmatrix} \begin{bmatrix} -1 & -1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \sqrt{2} & 1/\sqrt{2} \\ 0 & \sqrt{3/2} \end{bmatrix}.$$