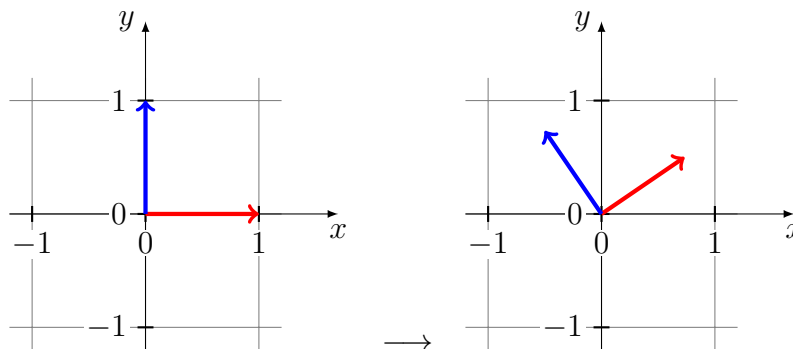


1. Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear transformation that rotates points (about the origin) 30° counterclockwise.

(a) What is the matrix for T ?



Remember the strategy to figure out the matrix for a transformation: you need to look at the two vectors $\mathbf{e}_1 = (1, 0)$ and $\mathbf{e}_2 = (0, 1)$, and figure out what the transformation does to these two. In this case, a little geometry shows us that the coordinates for the rotated vectors on the right are

$$T(\mathbf{e}_1) = \left(\frac{\sqrt{3}}{2}, \frac{1}{2} \right), \quad T(\mathbf{e}_2) = \left(-\frac{1}{2}, \frac{\sqrt{3}}{2} \right)$$

To get the matrix for T , we need to take $T(\mathbf{e}_1)$ and insert it as the first column of the matrix, and take $T(\mathbf{e}_2)$ and insert it as the second column:

$$A = \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

(b) Is the linear transformation T one-to-one? Why or why not?

Remember that T is one-to-one if every \mathbf{b} in \mathbb{R}^2 is the image of *at most one* \mathbf{x} . This is the case for this transformation: given any vector \mathbf{b} , there is never more than one vector that gets sent to \mathbf{b} , since the map is just a rotation.

You could also check this using row reduction on the matrix you found in (a): you need to verify that the columns of A are linearly independent.

2. Consider the matrices:

$$A = \begin{bmatrix} 1 & -1 \\ 0 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{bmatrix}.$$

For each of AB and BA , either compute it or explain why it is not defined.

$$AB = \begin{bmatrix} 1 & -1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{bmatrix} = [-1 \quad 1 \quad 04 \quad 4 \quad 2]$$

$$BA = \begin{bmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 2 \end{bmatrix} = \text{Not defined: the numbers of rows of the}$$

second matrix is not equal to the number of columns of the first one.